子午工程 GPS-TEC 监测仪设备

数据文件格式说明

子午工程数据中心

1 数据文件交换借口

1.1 数据文件定义

每一类数据文件描述如下表：

序号	数据文件名称	数据文件描述	数据级别	文件格式	类型编码	存储时间分割类型	数据文件文件名	设备→节点站				节点站→子午工程数据中心			
								是否打包传输	压缩包文件名称	传输时频模式	通讯确认	是否打包传输	压缩包文件名称	传输时频模式	通讯确认
01	TEC 数据文件	电离层 TEC 值	二级科学数据	二进制	D	01H	HMT_GPS01_DDD_L21_01H_20080503100000.TEC	No	/	1 小时	No	No	/	1 小时	No
02	GPS 原始观测数据文件	双频 GPS 载波相位与伪距信息	原始数据	RINEX	D	24 小时	XXX_GPS01_DOG_L01_01D_YYYYLLDDHHMMSS.RNX	No	/	24 小时	No	No	/	24 小时	No
03	GPS 原始观测数据文件	双频 GPS 载波相位与伪距信息	原始数据	RINEX	D	01H	FKT_GPS01_DOG_L01_01H_20071120123000.RNX	No	/	1 小时	No	No	/	1 小时	No

XXX 为台站名称，如 MHT，SSL，ZLT，SYS。

1.2 数据文件－格式描述

1.2.1 电离层 TEC 观测数据

电离层 TEC 观测结果以二进制格式储存，具体数据格式如下。

序列	名称		数据类型	偏移量	信息长度	无效缺省值	备注
1	头信息 (共 48byte)	观测站 ID	Char	0	4		
		观测站名称	Char	4	20		
		观测站经度	Float	24	4		
		观测站纬度	Float	28	4		
		当前 TEC 数据的条数	Int	32	4		
		预留	Char	36..	12		
2	数据区 (共 48byte)	第 1 条 TEC 数据	float	48	4	999	每五分钟一条数据共 12 条数据
		第 2 条 TEC 数据	float	52	4	999	
		…….	……	……	…..	999	
		第 12 条 TEC 数据	float	92	4	999	

1.2.2 GPS 原始观测数据

原始观测数据为国际通用的 RINEX 格式存储。具体格式描述见附件一。

1.3 其他要求

无

附件一

RINEX: The Receiver Independent Exchange Format Version 2

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(Revision, April 1993)
(Clarification December 1993)
(Doppler Definition: January 1994)
(PR Clarification: October 1994)
(Wlfact Clarification: February 1995)
(Event Time Frame Clarification: May 1996)
(Minor errors in the examples A7/A8: May 1996)
(Naming convention for compressed met files; January 1997)
(Continuation line clarifications: April 1997)
(GLONASS Extensions: April 1997)
(Met sensor description and position records: April 1997)
(Wavelength factor clarifications: April 1997)

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0. INTRODUCTION

0.1 First Revision

This paper is a revised version of the one published by W. Gurtner and G. Mader in the CSTG GPS Bulletin of September/October 1990. The main reason for a revision is the new treatment of antispoofing data by the RINEX format (see chapter 7). Chapter 4 gives a recommendation for data compression procedures, especially useful when large amounts of data are exchanged through computer networks. In Table A3 in the original paper the definiton of the "PGM / RUN BY / DATE" navigation header record was missing, although the example showed it. The redefinition of AODE/AODC to IODE/IODC also asks for an update of the format description. For consistency reasons we also defined a Version 2 format for the Meteorological Data files (inclusion of a END OF HEADER record and an optional MARKER NUMBER record).

* The slight modification (or rather the definition of a bit in the Loss *
* of Lock Indicator unused so far) to flag AS data is so small a change *
* that we decided to NOT increase the version number! *

0.2 Later Revisions:

* URA Clarification (10-Dec-93):

The user range accuracy in the Navigation Message File did not contain a definition of the units: There existed two ways of interpretation: Either the 4 bit value from the original message or the converted value in meters according to GPS ICD-200. In order to simplify the interpretation for the user of the RINEX files I propose the bits to be converted into meters prior to RINEX file creation.

* GLONASS Extensions:

In March 1997 a proposal for extensions to the current RINEX definitions based on experiences collected with GLONASS only and mixed GPS/GLONASS data files was circulated among several instrument manufacturers and software developers. The results of the call for comments have been worked into this document. A separate document (glonass.txt) summarizes just the necessary extensions.

* A blank satellite identifier is allowed in pure GPS files only

* Met sensor description and position records were added to facilitate the precise use of met values.

* Description and examples for wavelength factors and their temporary changes (bit 1 of LLI) clarified.

In order to have all the available information about RINEX in one place we also included parts of earlier papers and a complete set of format definiton tables and examples.

1. THE PHILOSOPHY OF RINEX

The first proposal for the "Receiver Independent Exchange Format" RINEX has been developed by the Astronomical Institute of the University of Berne for the easy exchange of the GPS data to be collected during the large European GPS campaign EUREF 89, which involved more than 60 GPS receivers of 4 different manufacturers. The governing aspect during the development was the following fact:

Most geodetic processing software for GPS data use a well-defined set of observables:

- the carrier-phase measurement at one or both carriers (actually being a measurement on the beat frequency between the received carrier of the satellite signal and a receiver-generated reference frequency).

- the pseudorange (code) measurement, equivalent to the difference of the time of reception (expressed in the time frame of the receiver) and the time of transmission (expressed in the time frame of the satellite) of a distinct satellite signal.

- the observation time being the reading of the receiver clock at the instant of validity of the carrier-phase and/or the code measurements.

Usually the software assumes that the observation time is valid for both the phase AND the code measurements, AND for all satellites observed.

Consequently all these programs do not need most of the information that is usually stored by the receivers: They need phase, code, and time in the above mentioned definitions, and some station-related information like station name, antenna height, etc.

2. GENERAL FORMAT DESCRIPTION

Currently the format consists of four ASCII file types:

1. Observation Data File
2. Navigation Message File
3. Meteorological Data File
4. GLONASS Navigation Message File

Each file type consists of a header section and a data section. The header section contains global information for the entire file and is placed at the beginning of the file. The header section contains header labels in columns 61-80 for each line contained in the header section. These labels are mandatory and must appear exactly as given in these descriptions and examples.

The format has been optimized for mimimum space requirements independent from the number of different observation types of a specific receiver by indicating in the header the types of observations to be stored. In computer systems allowing variable record lengths the observation records may then be kept as short as possible. The maximum record length is 80 bytes per record.

Each Observation file and each Meteorological Data file basically contain the data from one site and one session. RINEX Version 2 also allows to include observation data from more than one site subsequently occupied by

a roving receiver in rapid static or kinematic applications.

If data from more than one receiver has to be exchanged it would not be economical to include the identical satellite messages collected by the different receivers several times. Therefore the Navigation Message File from one receiver may be exchanged or a composite Navigation Message File created containing non-redundant information from several receivers in order to make the most complete file.

The format of the data records of the RINEX Version 1 Navigation Message file is identical to the former NGS exchange format.

The actual format descriptions as well as examples are given in the Tables at the end of the paper.

3. DEFINITION OF THE OBSERVABLES

GPS observables include three fundamental quantities that need to be defined: Time, Phase, and Range.

TIME:

The time of the measurement is the receiver time of the received signals. It is identical for the phase and range measurements and is identical for all satellites observed at that epoch. It is expressed in GPS time (not Universal Time).

PSEUDO-RANGE:

The pseudo-range (PR) is the distance from the receiver antenna to the satellite antenna including receiver and satellite clock offsets (and other biases, such as atmospheric delays):

```
PR  =  distance +
       c * (receiver clock offset - satellite clock offset +
            other biases)
```

so that the pseudo-range reflects the actual behavior of the receiver and satellite clocks. The pseudo-range is stored in units of meters.

See also clarifications for pseudoranges in mixed GPS/GLONASS files in chapter 8.1.

PHASE:

The phase is the carrier-phase measured in whole cycles at both L1 and L2. The half-cycles measured by sqaring-type receivers must be converted to whole cycles and flagged by the wavelength factor in the header section.

The phase changes in the same sense as the range (negative doppler). The phase observations between epochs must be connected by including the integer number of cycles. The phase observations will not contain any systematic drifts from intentional offsets of the reference oscillators.

The observables are not corrected for external effects like atmospheric refraction, satellite clock offsets, etc.

If the receiver or the converter software adjusts the measurements using the real-time-derived receiver clock offsets dT(r), the consistency of the 3 quantities phase / pseudo-range / epoch must be maintained, i.e. the receiver clock correction should be applied to all 3 observables:

Time(corr) = Time(r) - dT(r)
PR(corr) = PR(r) - dT(r)*c
phase(corr) = phase(r) - dT(r)*freq

DOPPLER:

The sign of the doppler shift as additional observable is defined as usual: Positive for approaching satellites.

4. THE EXCHANGE OF RINEX FILES:

We recommend using the following naming convention for RINEX files:

ssssdddf.yyt

ssss: 4-character station name designator
ddd: day of the year of first record
f: file sequence number within day
0: file contains all the existing data of the current day
yy: year
t: file type:
O: Observation file
N: Navigation file
M: Meteorological data file

G: GLONASS Navigation file

To exchange RINEX files on magnetic tapes we recommend using the following tape format:

- Non-label; ASCII; fixed record length: 80 characters;
  block size: 8000

- First file on tape contains list of files using above-mentioned
  naming conventions

When data transmission times or storage volumes are critical we recommend compressing the files prior to storage or transmission using the UNIX "compress" und "uncompress" programs. Compatible routines are available on VAX/VMS and PC/DOS systems, as well.

Proposed naming conventions for the compressed files:

System	Obs files	GPS Nav Files	GLONASS Nav Files	Met Files
UNIX	ssssdddf.yyO.Z	ssssdddf.yyN.Z	ssssdddf.yyG.Z	ssssdddf.yyM.Z
VMS	ssssdddf.yyO_Z	ssssdddf.yyN_Z	ssssdddf.yyG_Z	ssssdddf.yyN_Z
DOS	ssssdddf.yyY	ssssdddf.yyX	ssssdddf.yyV	ssssdddf.yyW

5. RINEX VERSION 2 FEATURES

The following section contains features that have been introduced for RINEX Version 2.

5.1 Satellite Numbers:

Version 2 has been prepared to contain GLONASS or other satellite systems' observations. Therefore we have to be able to distinguish the satellites of the different systems: We precede the 2-digit satellite number with a system identifier.

snn

s: satellite system identifier
- G or blank : GPS
- R : GLONASS
- T : Transit

nn: PRN (GPS), almanac number (GLONASS)
or two-digit Transit satellite number

Note: G is mandatory in mixed GPS/GLONASS files

(blank default modified in April 1997)

5.2 Order of the Header Records:

As the record descriptors in columns 61-80 are mandatory, the programs reading a RINEX Version 2 header are able to decode the header records with formats according to the record descriptor, provided the records have been first read into an internal buffer.

We therefore propose to allow free ordering of the header records, with the following exceptions:

- The "RINEX VERSION / TYPE" record must be the first record in a file

- The default "WAVELENGTH FACT L1/2" record (if present) should precede all records defining wavelength factors for individual satellites

- The "# OF SATELLITES" record (if present) should be immediately followed by the corresponding number of "PRN / # OF OBS" records. (These records may be handy for documentary purposes. However, since they may only be created after having read the whole raw data file we define them to be optional.

5.3 Missing Items, Duration of the Validity of Values

Items that are not known at the file creation time can be set to zero or blank or the respective record may be completely omitted. Consequently items of missing header records will be set to zero or blank by the program reading RINEX files. Each value remains valid until changed by an additional header record.

5.4. Event Flag Records

The "number of satellites" also corresponds to the number of records of the same epoch followed. Therefore it may be used to skip the appropriate number of records if certain event flags are not to be evaluated in detail.

5.5 Receiver Clock Offset

A large number of users asked to optionally include a receiver-derived clock offset into the RINEX format. In order to prevent confusion and redundancy, the receiver clock offset (if present) should report the value

that has been used to correct the observables according to the formulae under item 1. It would then be possible to reconstruct the original observations if necessary. As the output format for the receiver-derived clock offset is limited to nanoseconds the offset should be rounded to the nearest nanosecond before it is used to correct the observables in order to guarantee correct reconstruction.

6. ADDITIONAL HINTS AND TIPS

Programs developed to read RINEX Version 1 files have to verify the version number. Version 2 files may look different (version number, END OF HEADER record, receiver and antenna serial number alphanumeric) even if they do not use any of the new features

We propose that routines to read RINEX Version 2 files automatically delete leading blanks in any CHARACTER input field. Routines creating RINEX Version 2 files should also left-justify all variables in the CHARACTER fields.

DOS, and other, files may have variable record lengths, so we recommend to first read each observation record into a 80-character blank string and decode the data afterwards. In variable length records, empty data fields at the end of a record may be missing, especially in the case of the optional receiver clock offset.

7. RINEX UNDER ANTISPOOFING (AS)

Some receivers generate code delay differences between the first and second frequency using cross-correlation techniques when AS is on and may recover the phase observations on L2 in full cycles. Using the C/A code delay on L1 and the observed difference it is possible to generate a code delay observation for the second frequency.

Other receivers recover P code observations by breaking down the Y code into P and W code.

Most of these observations may suffer from an increased noise level. In order to enable the postprocessing programs to take special actions, such AS-infected observations are flagged using bit number 2 of the Loss of Lock Indicators (i.e. their current values are increased by 4).

8. GLONASS Extensions

8.1 RINEX Observation file

8.1.1 Time System Identifier

RINEX Version 2 needs one major supplement, the explicit definition of the time system:

GLONASS is basically running on UTC (or, more precisely, GLONASS system time linked to UTC(SU)), i.e. the time tags are given in UTC and not GPS time.
In order to remove possible misunderstandings and ambiguities, the header records "TIME OF FIRST OBS" and (if present) "TIME OF LAST OBS" in GLONASS and GPS observation files _can_, in mixed GLONASS/GPS observation files _must_ contain a time system identifier defining the system that all time tags in the file are referring to: "GPS" to identify GPS time, "GLO" to identify the GLONASS UTC time system. Pure GPS files default to GPS and pure GLONASS files default to GLO.

Format definitions see Table A1.

Hence, the two possible time tags differ by the current number of leap seconds.

In order to have the current number of leap seconds available we recommend to include a LEAP SECOND line into the RINEX header.

If there are known non-integer biases between the "GPS receiver clock" and "GLONASS receiver clock" in the same receiver, they should be applied. In this case the respective code and phase observations have to be corrected, too (c * bias if expressed in meters).

Unknown such biases will have to be solved for during the post processing

The small differences (modulo 1 second) between GLONASS system time, UTC(SU), UTC(USNO) and GPS system time have to be dealt with during the post-processing and not before the RINEX conversion. It may also be necessary to solve for remaining differences during the post-processing.

8.1.2 Pseudorange Definition

The pseudorange (code) measurement is defined to be equivalent to the difference of the time of reception (expressed in the time frame of the receiver) and the time of transmission (expressed in the time frame of the satellite) of a distinct satellite signal.

If a mixed-mode GPS/GLONASS receiver refers all pseudorange observations to one receiver clock only,

- the raw GLONASS pseudoranges will show the current number of leap seconds between GPS time and GLONASS time if the receiver clock is running in the GPS time frame

- the raw GPS pseudoranges will show the negative number of leap seconds between GPS time and GLONASS time if the receiver clock is running in the GLONASS time frame

In order to avoid misunderstandings and to keep the code observations within the format fields, the pseudoranges must be corrected in this case as follows:

PR(GPS) := PR(GPS) + c * leap_seconds if generated with a receiver clock running in the GLONASS time frame

PR(GLO) := PR(GLO) - c * leap_seconds if generated with a receiver clock running in the GPS time frame

to remove the contributions of the leap seconds from the pseudoranges.

"leap_seconds" is the actual number of leap seconds between GPS and GLONASS (UTC) time, as broadcast in the GPS almanac and distributed in Circular T of BIPM.

8.1.3 More than 12 satellites per epoch

The format of the epoch / satellite line in the observation record part of the RINEX Observation files has only been defined for up to 12 satellites per epoch. We explicitly define now the format of the continuation lines, see table A2.

8.2 RINEX Navigation Files for GLONASS

As the GLONASS navigation message differs in contents from the GPS message too much, a special GLONASS navigation message file format has been defined.

The header section and the first data record (epoch, satellite clock information) is similar to the GPS navigation file. The following records contain the satellite position, velocity and acceleration, the clock and frequency biases as well as auxiliary information as health, satellite

frequency (channel), age of the information.

*** In order to use the same sign conventions for the time and frequency bias as in the GPS navigation files, the broadcast GLONASS values are multiplied by -1.

The time tags in the GLONASS navigation files are given in UTC (i.e. _not_ Moscow time or GPS time).

Filenaming convention: See above.

9. REFERENCES

Evans, A. (1989): "Summary of the Workshop on GPS Exchange Formats." Proceedings of the Fifth International Geodetic Symposium on Satellite Systems, pp. 917ff, Las Cruces.

Gurtner, W., G. Mader, D. Arthur (1989): "A Common Exchange Format for GPS Data." CSTG GPS Bulletin Vol.2 No.3, May/June 1989, National Geodetic Survey, Rockville.

Gurtner, W., G. Mader (1990): "The RINEX Format: Current Status, Future Developments." Proceedings of the Second International Symposium of Precise Positioning with the Global Positioning system, pp. 977ff, Ottawa.

Gurtner, W., G. Mader (1990): "Receiver Independent Exchange Format Version 2." CSTG GPS Bulletin Vol.3 No.3, Sept/Oct 1990, National Geodetic Survey, Rockville.

10. RINEX VERSION 2 FORMAT DEFINITIONS AND EXAMPLES

TABLE A1

OBSERVATION DATA FILE - HEADER SECTION DESCRIPTION

HEADER LABEL (Columns 61-80)	DESCRIPTION	FORMAT
RINEX VERSION / TYPE	- Format version (2)	I6,14X,
	- File type ('O' for Observation Data)	A1,19X,
	- Satellite System: blank or 'G': GPS 'R': GLONASS	A1,19X

		'T': NNSS Transit	
		'M': Mixed	
	PGM / RUN BY / DATE	- Name of program creating current file	A20,
		- Name of agency creating current file	A20,
		- Date of file creation	A20
*		COMMENT	Comment line(s)	A60	*
	|MARKER NAME	Name of antenna marker	A60
*		MARKER NUMBER	Number of antenna marker	A20	*
	|OBSERVER / AGENCY	Name of observer / agency	A20,A40
	|REC # / TYPE / VERS	Receiver number, type, and version	3A20
			(Version: e.g. Internal Software Version)	
	|ANT # / TYPE	Antenna number and type	2A20
	|APPROX POSITION XYZ	Approximate marker position (WGS84)	3F14.4
	|ANTENNA: DELTA H/E/N	- Antenna height: Height of bottom	3F14.4
			surface of antenna above marker	
			- Eccentricities of antenna center	
			relative to marker to the east	
			and north (all units in meters)	
	|WAVELENGTH FACT L1/2	- Wavelength factors for L1 and L2	2I6,
			1: Full cycle ambiguities	
			2: Half cycle ambiguities (squaring)	
			0 (in L2): Single frequency instrument	
			- Number of satellites to follow in list	I6,
			for which these factors are valid.	
			0 or blank: Default wavelength factors	
			for all satellites not contained in	
			such a list.	
			- List of PRNs (satellite numbers)	7(3X,A1,I2)
			Repeat record if necessary	
	|# / TYPES OF OBSERV	- Number of different observation types	I6,
			stored in the file	
			- Observation types	9(4X,A2)

```
 |                    |                                         |            |
 |                    |   If more than 9 observation types:     |            |
 |                    |     Use continuation line(s)            |6X,9(4X,A2) |
 |                    |                                         |            |
 |                    | The following observation types are     |            |
 |                    | defined in RINEX Version 2:             |            |
 |                    |                                         |            |
 |                    | L1, L2: Phase measurements on L1 and L2 |            |
 |                    | C1    : Pseudorange using C/A-Code on L1 |           |
 |                    | P1, P2: Pseudorange using P-Code on L1,L2|           |
 |                    | D1, D2: Doppler frequency on L1 and L2  |            |
 |                    | T1, T2: Transit Integrated Doppler on   |            |
 |                    |         150 (T1) and 400 MHz (T2)       |            |
 |                    |                                         |            |
 |                    | Observations collected under Antispoofing|           |
 |                    | are converted to "L2" or "P2" and flagged|           |
 |                    | with bit 2 of loss of lock indicator    |            |
 |                    | (see Table A2).                         |            |
 |                    |                                         |            |
 |                    | Units : Phase       : full cycles       |            |
 |                    |         Pseudorange : meters            |            |
 |                    |         Doppler     : Hz                |            |
 |                    |         Transit     : cycles            |            |
 |                    |                                         |            |
 |                    | The sequence of the types in this record |           |
 |                    | has to correspond to the sequence of the |           |
 |                    | observations in the observation records |            |
 +--------------------+-----------------------------------------+------------+
*|INTERVAL            | Observation interval in seconds         |     I6     |*
 +--------------------+-----------------------------------------+------------+
 |TIME OF FIRST OBS   | - Time of first observation record      | 5I6,F12.6, |
 |                    |   (4-digit-year, month,day,hour,min,sec) |           |
 |                    | - Time system: GPS (=GPS time system)   |   6X,A3    |
 |                    |                GLO (=UTC time system)   |            |
 |                    |   Compulsory in mixed GPS/GLONASS files |            |
 |                    |   Defaults: GPS for pure GPS files      |            |
 |                    |             GLO for pure GLONASS files  |            |
 +--------------------+-----------------------------------------+------------+
*|TIME OF LAST OBS    | - Time of last  observation record      | 5I6,F12.6, |*
 |                    |   (4-digit-year, month,day,hour,min,sec) |           |
 |                    | - Time system: GPS (=GPS time system)   |   6X,A3    |
 |                    |                GLO (=UTC time system)   |            |
 |                    |   Compulsory in mixed GPS/GLONASS files |            |
 |                    |   Defaults: GPS for pure GPS files      |            |
```

	GLO for pure GLONASS files	
*|LEAP SECONDS	Number of leap seconds since 6-Jan-1980 | Recommended for mixed GPS/GLONASS files	I6	*
*|# OF SATELLITES	Number of satellites, for which observations are stored in the file	I6	*
*|PRN / # OF OBS	PRN (sat.number), number of observations for each observation type indicated in the "# / TYPES OF OBSERV" - record.	3X,A1,I2,9I6	*
	If more than 9 observation types: Use continuation line(s)	6X,9I6	
	This record is (these records are) repeated for each satellite present in the data file		
END OF HEADER	Last record in the header section.	60X	

Records marked with * are optional

TABLE A2

OBSERVATION DATA FILE - DATA RECORD DESCRIPTION

OBS. RECORD	DESCRIPTION	FORMAT
EPOCH/SAT or EVENT FLAG	- Epoch : year (2 digits), month,day,hour,min,sec - Epoch flag 0: OK 1: power failure between previous and current epoch 1: Event flag	5I3,F11.7, I3,
	- Number of satellites in current epoch	I3,
	- List of PRNs (sat.numbers) in current epoch	12(A1,I2),
	- receiver clock offset (seconds, optional)	F12.9
	If more than 12 satellites: Use continuation line(s)	32X, 12(A1,I2)

	If EVENT FLAG record (epoch flag 1):	
	- Event flag:	
	2: start moving antenna	
	3: new site occupation (end of kinem. data)	
	(at least MARKER NAME record follows)	
	4: header information follows	
	5: external event (epoch is significant,	
	same time frame as observation time tags)	
	6: cycle slip records follow to optionally	
	report detected and repaired cycle slips	
	(same format as OBSERVATIONS records;	
	slip instead of observation; LLI and	
	signal strength blank)	
	- "Number of satellites" contains number of	
	records to follow (0 for event flags 2,5)	
OBSERVATIONS	- Observation - LLI - Signal strength	rep. within record for each obs.type (same seq as given in header)	m(F14.3, I1, I1)
	If more than 5 observation types (=80 char):	
	continue observations in next record.	
	This record is (these records are) repeated for	
	each satellite given in EPOCH/SAT - record.	
	Observations:	
	Phase : Units in whole cycles of carrier	
	Code : Units in meters	
	Missing observations are written as 0.0	
	or blanks.	
	Loss of lock indicator (LLI). Range: 0-7	
	0 or blank: OK or not known	
	Bit 0 set : Lost lock between previous and	
	current observation: cycle slip	
	possible	
	Bit 1 set : Opposite wavelength factor to the	
	one defined for the satellite by a	
	previous WAVELENGTH FACT L1/2 line.	
	Valid for the current epoch only.	
	Bit 2 set : Observation under Antispoofing	
	(may suffer from increased noise)	
	Bits 0 and 1 for phase only.	

	Signal strength projected into interval 1-9:		
	1: minimum possible signal strength		
	5: threshold for good S/N ratio		
	9: maximum possible signal strength		
	0 or blank: not known, don't care		

TABLE A3

NAVIGATION MESSAGE FILE - HEADER SECTION DESCRIPTION

HEADER LABEL (Columns 61-80)	DESCRIPTION	FORMAT
RINEX VERSION / TYPE	- Format version (2)	I6,14X,
	- File type ('N' for Navigation data)	A1,19X
PGM / RUN BY / DATE	- Name of program creating current file	A20,
	- Name of agency creating current file	A20,
	- Date of file creation	A20
*COMMENT	Comment line(s)	A60 *
*ION ALPHA	Ionosphere parameters A0-A3 of almanac (page 18 of subframe 4)	2X,4D12.4 *
*ION BETA	Ionosphere parameters B0-B3 of almanac	2X,4D12.4 *
*DELTA-UTC: A0,A1,T,W	Almanac parameters to compute time in UTC (page 18 of subframe 4) A0,A1: terms of polynomial T : reference time for UTC data W : UTC reference week number	3X,2D19.12, 2I9
*LEAP SECONDS	Delta time due to leap seconds	I6 *
END OF HEADER	Last record in the header section.	60X

Records marked with * are optional

TABLE A4

NAVIGATION MESSAGE FILE - DATA RECORD DESCRIPTION

OBS. RECORD	DESCRIPTION	FORMAT
PRN / EPOCH / SV CLK	- Satellite PRN number	I2,
	- Epoch: Toc - Time of Clock	
	year (2 digits)	5I3,
	month	
	day	
	hour	
	minute	
	second	F5.1,
	- SV clock bias (seconds)	3D19.12
	- SV clock drift (sec/sec)	
	- SV clock drift rate (sec/sec2)	
BROADCAST ORBIT - 1	- IODE Issue of Data, Ephemeris	3X,4D19.12
	- Crs (meters)	
	- Delta n (radians/sec)	
	- M0 (radians)	
BROADCAST ORBIT - 2	- Cuc (radians)	3X,4D19.12
	- e Eccentricity	
	- Cus (radians)	
	- sqrt(A) (sqrt(m))	
BROADCAST ORBIT - 3	- Toe Time of Ephemeris	3X,4D19.12
	(sec of GPS week)	
	- Cic (radians)	
	- OMEGA (radians)	
	- CIS (radians)	
BROADCAST ORBIT - 4	- i0 (radians)	3X,4D19.12
	- Crc (meters)	
	- omega (radians)	
	- OMEGA DOT (radians/sec)	
BROADCAST ORBIT - 5	- IDOT (radians/sec)	3X,4D19.12
	- Codes on L2 channel	
	- GPS Week # (to go with TOE)	
	- L2 P data flag	

BROADCAST ORBIT - 6	- SV accuracy (meters)	3X,4D19.12
	- SV health (MSB only)	
	- TGD (seconds)	
	- IODC Issue of Data, Clock	
BROADCAST ORBIT - 7	- Transmission time of message	3X,4D19.12
	(sec of GPS week, derived e.g.	
	from Z-count in Hand Over Word (HOW)	
	- spare	
	- spare	
	- spare	

TABLE A5

METEOROLOCICAL DATA FILE - HEADER SECTION DESCRIPTION

HEADER LABEL (Columns 61-80)	DESCRIPTION	FORMAT
RINEX VERSION / TYPE	- Format version (2)	I6,14X,
	- File type ('M' for Meteorological Data)	A1,39X
PGM / RUN BY / DATE	- Name of program creating current file	A20,
	- Name of agency creating current file	A20,
	- Date of file creation	A20
*COMMENT	Comment line(s)	A60 *
MARKER NAME	Station Name	A60
	(preferably identical to MARKER NAME in the associated Observation File)	
*MARKER NUMBER	Station Number	A20 *
	(preferably identical to MARKER NUMBER in the associated Observation File)	
# / TYPES OF OBSERV	- Number of different observation types	I6,
	stored in the file	
	- Observation types	9(4X,A2)
	The following meteorological observation	

	types are defined in RINEX Version 2:	
	PR : Pressure (mbar)	
	TD : Dry temperature (deg Celsius)	
	HR : Relative Humidity (percent)	
	ZW : Wet zenith path delay (millimeters)	
	(for WVR data)	
	The sequence of the types in this record	
	must correspond to the sequence of the	
	measurements in the data records	
	If more than 9 observation types are	
	being used, use continuation lines with	
	format (6X,9(4X,A2))	

MET SENSOR MOD/TYPE	Description of the met sensor	
	- Model (manufacturer)	A20,
	- Type	A20,6X,
	- Accuracy (same units as obs values)	F7.1,4X,
	- Observation type	A2,1X
	Record is repeated for each observation	
	type found in # / TYPES OF OBSERV record	

MET SENSOR POS XYZH	Approximate position of the met sensor	
	- Geocentric coordinates X,Y,Z (ITRF	3F14.4,
	- Ellipsoidal height H or WGS-84)	1F14.4,
	- Observation type	1X,A2,1X
	Set X,Y,Z to zero if not known.	
	Make sure H refers to ITRF or WGS-84!	
	Record required for barometer,	
	recommended for other sensors.	

END OF HEADER	Last record in the header section.	60X

TABLE A6

METEOROLOGICAL DATA FILE - DATA RECORD DESCRIPTION

OBS. RECORD	DESCRIPTION	FORMAT

EPOCH / MET	- Epoch in GPS time (not local time!)	6I3,
	year (2 digits), month,day,hour,min,sec	
	- Met data in the same sequence as given in the header	mF7.1
	More than 8 met data types: Use continuation lines	4X,10F7.1,3X

TABLE A7

OBSERVATION DATA FILE - EXAMPLE

```
----|---1|0---|---2|0---|---3|0---|---4|0---|---5|0---|---6|0---|---7|0---|---8|

     2                    OBSERVATION  DATA        M  (MIXED)                RINEX  VERSION  /
TYPE
BLANK OR G = GPS,    R = GLONASS,    T = TRANSIT,    M = MIXED       COMMENT
XXRINEXO V9.9           AIUB                    22-APR-93 12:43        PGM / RUN BY / DATE
EXAMPLE OF A MIXED RINEX FILE                                          COMMENT
A 9080                                                                 MARKER NAME
9080.1.34                                                              MARKER NUMBER
BILL SMITH              ABC INSTITUTE                                  OBSERVER / AGENCY
X1234A123               XX                      ZZZ                    REC # / TYPE / VERS
234                     YY                                             ANT # / TYPE
  4375274.          587466.         4589095.                         APPROX POSITION XYZ
          .9030             .0000             .0000                  ANTENNA: DELTA H/E/N
     1    1                                                           WAVELENGTH FACT L1/2
     1    2    6    G14    G15    G16    G17    G18    G19            WAVELENGTH  FACT
L1/2
     4    P1    L1    L2    P2                                        # / TYPES OF OBSERV
    18                                                               INTERVAL
  1990     3    24    13    10    36.000000                         TIME OF FIRST OBS
                                                                     END OF HEADER
 90   3 24 13 10 36.0000000  0   3G12G 9G 6                                -.123456789
  23629347.915                .300 8            -.353      23629364.158
  20891534.648               -.120 9            -.358      20891541.292
  20607600.189               -.430 9             .394      20607605.848
 90   3 24 13 10 50.0000000  4   4
     1    2    2    G 9    G12                                       WAVELENGTH FACT L1/2
  *** WAVELENGTH FACTOR CHANGED FOR 2 SATELLITES ***          COMMENT
```

```
      NOW 8 SATELLITES HAVE WL FACT 1 AND 2!                COMMENT
                                                            COMMENT
 90    3 24 13 10 54.0000000    0    5G12G 9G 6R21R22                -.123456789
   23619095.450          -53875.632 8       -41981.375       23619112.008
   20886075.667          -28688.027 9       -22354.535       20886082.101
   20611072.689           18247.789 9        14219.770       20611078.410
   21345678.576           12345.567 5
   22123456.789           23456.789 5
 90    3 24 13 11    0.0000000    2
                                    4    1
        *** FROM NOW ON KINEMATIC DATA! ***                   COMMENT
 90    3 24 13 11 48.0000000    0    4G16G12G 9G 6                   -.123456789
   21110991.756           16119.980 7        12560.510       21110998.441
   23588424.398         -215050.557 6      -167571.734       23588439.570
   20869878.790         -113803.187 8       -88677.926       20869884.938
   20621643.727           73797.462 7        57505.177       20621649.276
                                    3    4
A 9080                                                      MARKER NAME
9080.1.34                                                   MARKER NUMBER
            .9030             .0000             .0000       ANTENNA: DELTA H/E/N
         -- THIS IS THE START OF A NEW SITE <--             COMMENT
 90    3 24 13 12    6.0000000    0    4G16G12G 6G 9                   -.123456987
   21112589.384           24515.877 6        19102.763 3    21112596.187
   23578228.338         -268624.234 7      -209317.284 4    23578244.398
   20625218.088           92581.207 7        72141.846 4    20625223.795
   20864539.693         -141858.836 8      -110539.435 5    20864545.943
 90    3 24 13 13    1.2345678    5    0
                                    4    1
        (AN EVENT FLAG WITH SIGNIFICANT EPOCH)               COMMENT
 90    3 24 13 14 12.0000000    0    4G16G12G 9G 6                   -.123456012
   21124965.133           89551.30216        69779.62654    21124972.2754
   23507272.372         -212616.150 7      -165674.789 5    23507288.421
   20828010.354         -333820.093 6      -260119.395 5    20828017.129
   20650944.902          227775.130 7       177487.651 4    20650950.363
                                    4    1
          *** ANTISPOOFING ON G 16 AND LOST LOCK              COMMENT
 90    3 24 13 14 12.0000000    6    2G16G 9
                          123456789.0          -9876543.5
                                0.0                  -0.5
                                    4    2
          ---> CYCLE SLIPS THAT HAVE BEEN APPLIED TO         COMMENT
               THE OBSERVATIONS                             COMMENT
 90    3 24 13 14 48.0000000    0    4G16G12G 9G 6                   -.123456234
   21128884.159          110143.144 7        85825.18545    21128890.7764
```

```
   23487131.045       -318463.297 7     -248152.72824    23487146.149
   20817844.743       -387242.571 6     -301747.22925    20817851.322
   20658519.895        267583.67817      208507.26234    20658525.869
                                   4    4
            ***     SATELLITE G 9     THIS EPOCH ON WLFACT 1 (L2)    COMMENT
            *** G 6 LOST LOCK AND THIS EPOCH ON WLFACT 2 (L2)    COMMENT
                        (OPPOSITE TO PREVIOUS SETTINGS)                COMMENT

----|---1|0---|---2|0---|---3|0---|---4|0---|---5|0---|---6|0---|---7|0---|---8|
```

TABLE A8

NAVIGATION MESSAGE FILE - EXAMPLE

```
----|---1|0---|---2|0---|---3|0---|---4|0---|---5|0---|---6|0---|---7|0---|---8|

       2                    N: GPS NAV DATA                                RINEX VERSION / TYPE
XXRINEXN V2.0           AIUB                    12-SEP-90 15:22       PGM / RUN BY / DATE
EXAMPLE OF VERSION 2 FORMAT                                            COMMENT
       .1676D-07     .2235D-07    -.1192D-06    -.1192D-06              ION ALPHA
       .1208D+06     .1310D+06    -.1310D+06    -.1966D+06              ION BETA
       .133179128170D-06    .107469588780D-12      552960          39 DELTA-UTC: A0,A1,T,W
       6                                                                LEAP SECONDS
                                                                        END OF HEADER
 6 90    8    2 17 51 44.0 -.839701388031D-03 -.165982783074D-10    .000000000000D+00
       .910000000000D+02    .934062500000D+02    .116040547840D-08    .162092304801D+00
       .484101474285D-05    .626740418375D-02    .652112066746D-05    .515365489006D+04
       .409904000000D+06 -.242143869400D-07    .329237003460D+00 -.596046447754D-07
       .111541663136D+01    .326593750000D+03    .206958726335D+01 -.638312302555D-08
       .307155651409D-09    .000000000000D+00    .551000000000D+03    .000000000000D+00
       .000000000000D+00    .000000000000D+00    .000000000000D+00    .910000000000D+02
       .406800000000D+06
13 90    8    2 19    0    0.0    .490025617182D-03    .204636307899D-11    .000000000000D+00
       .133000000000D+03 -.963125000000D+02    .146970407622D-08    .292961152146D+01
      -.498816370964D-05    .200239347760D-02    .928156077862D-05    .515328476143D+04
       .414000000000D+06 -.279396772385D-07    .243031939942D+01 -.558793544769D-07
       .110192796930D+01    .271187500000D+03 -.232757915425D+01 -.619632953057D-08
      -.785747015231D-11    .000000000000D+00    .551000000000D+03    .000000000000D+00
       .000000000000D+00    .000000000000D+00    .000000000000D+00    .389000000000D+03
       .410400000000D+06

----|---1|0---|---2|0---|---3|0---|---4|0---|---5|0---|---6|0---|---7|0---|---8|
```

+---+
| TABLE A9 |
| METEOROLOGICAL DATA FILE - EXAMPLE |
+---+

```
----|---1|0---|---2|0---|---3|0---|---4|0---|---5|0---|---6|0---|---7|0---|---8|

     2                    METEOROLOGICAL  DATA                            RINEX  VERSION  /
TYPE
XXRINEXM V9.9          AIUB                      3-APR-96 00:10       PGM / RUN BY / DATE
EXAMPLE OF A MET DATA FILE                                              COMMENT
A 9080                                                                MARKER NAME
     3      PR      TD      HR                                          # / TYPES OF OBSERV
PAROSCIENTIFIC        740-16B                          0.2       PR SENSOR MOD/TYPE/ACC
HAENNI                                                 0.1       TD SENSOR MOD/TYPE/ACC
ROTRONIC              I-240W                           5.0       HR SENSOR MOD/TYPE/ACC
         0.0              0.0              0.0          1234.5678 PR SENSOR POS XYZ/H
                                                                    END OF HEADER
 96   4   1   0   0 15   987.1     10.6     89.5
 96   4   1   0   0 30   987.2     10.9     90.0
 96   4   1   0   0 45   987.1     11.6     89.0

----|---1|0---|---2|0---|---3|0---|---4|0---|---5|0---|---6|0---|---7|0---|---8|
```

+---+
| TABLE A10 |
| GLONASS NAVIGATION MESSAGE FILE - HEADER SECTION DESCRIPTION |

HEADER LABEL (Columns 61-80)	DESCRIPTION	FORMAT
RINEX VERSION / TYPE	- Format version (2)	I6,14X,
	- File type ('G' = GLONASS nav mess data)	A1,39X
PGM / RUN BY / DATE	- Name of program creating current file	A20,
	- Name of agency creating current file	A20,
	- Date of file creation (dd-mmm-yy hh:mm)	A20
*COMMENT	Comment line(s)	A60 *

*|CORR TO SYSTEM TIME	- Time of reference for system time corr	|*
	(year, month, day)	3I6,
	- Correction to system time scale (sec)	3X,D19.12
	to correct GLONASS system time to	
	UTC(SU)	
*|LEAP SECONDS	Number of leap seconds since 6-Jan-1980	I6 |*
|END OF HEADER	Last record in the header section.	60X

Records marked with * are optional

TABLE A11

GLONASS NAVIGATION MESSAGE FILE - DATA RECORD DESCRIPTION

OBS. RECORD	DESCRIPTION	FORMAT
|PRN / EPOCH / SV CLK|	- Satellite almanac number	I2,
	- Epoch of ephemerides (UTC)	
	- year (2 digits)	5I3,
	- month	
	- day	
	- hour	
	- minute	
	- second	F5.1,
	- SV clock bias (sec) (-tau)	D19.12
	- SV relative frequency bias (-gamma)	D19.12
	- message frame time (sec of day UTC)	D19.12
| BROADCAST ORBIT - 1|	- Satellite position X (km)	3X,4D19.12
	- velocity X dot (km/sec)	
	- X acceleration (km/sec2)	
	- health (0=OK) (Bn)	
| BROADCAST ORBIT - 2|	- Satellite position Y (km)	3X,4D19.12
	- velocity Y dot (km/sec)	
	- Y acceleration (km/sec2)	
	- frequency number (1-24)	

BROADCAST ORBIT - 3	- Satellite position Z (km)	3X,4D19.12
	- velocity Z dot (km/sec)	
	- Z acceleration (km/sec2)	
	- Age of oper. information (days) (E)	

TABLE A12

GLONASS NAVIGATION MESSAGE FILE - EXAMPLE

```
----|---1|0---|---2|0---|---3|0---|---4|0---|---5|0---|---6|0---|---7|0---|---8|

     2                    GLONASS  NAVMESS  DATA                         RINEX  VERSION  /
TYPE
XXRINEXN V1.3 VAX      University of Berne 30-AUG-93 17:57        PGM / RUN BY / DATE
  1993        8        7      -0.141188502312D-04                        CORR TO SYSTEM TIME
                                                                          END OF HEADER
 1 93    8    7 15 15    0.0-0.161942094564D-03 0.181898940355D-11 0.542700000000D+05
      0.129469794922D+05-0.130014419556D+01 0.186264514923D-08 0.000000000000D+00
     -0.380712744141D+04 0.266516971588D+01 0.000000000000D+00 0.170000000000D+02
      0.216525634766D+05 0.124328994751D+01-0.186264514923D-08 0.000000000000D+00
17 93    8    7 15 15    0.0 0.717733055353D-04 0.272848410532D-11 0.542700000000D+05
      0.305286718750D+04 0.311648464203D+01 0.000000000000D+00 0.000000000000D+00
     -0.108431787109D+05-0.317855834961D+00 0.000000000000D+00 0.210000000000D+00
      0.229024404297D+05-0.575817108154D+00-0.186264514923D-08 0.000000000000D+00
 7 93    8    7 15 15    0.0-0.902833417058D-04 0.181898940355D-11 0.542700000000D+05
     -0.548300732422D+04-0.442504882813D+00-0.931322574615D-09 0.000000000000D+00
      0.227251596680D+05 0.131087875366D+01-0.931322574615D-09 0.130000000000D+00
      0.998504833984D+04-0.323978710175D+01-0.931322574615D-09 0.000000000000D+00
 2 93    8    7 15 15    0.0-0.975374132395D-04 0.181898940355D-11 0.542700000000D+05
      0.138356103516D+05-0.716581344604D+00 0.279396772385D-08 0.000000000000D+00
     -0.190140761719D+05 0.116566944122D+01 0.000000000000D+00 0.500000000000D+01
      0.991978125000D+04 0.322995281219D+01 0.000000000000D+00 0.000000000000D+00
 8 93    8    7 15 15    0.0-0.292631797493D-03 0.363797880709D-11 0.542700000000D+05
      0.419437841797D+04-0.111876964569D+01 0.000000000000D+00 0.000000000000D+00
      0.141901040039D+05 0.262095737457D+01-0.931322574615D-09 0.200000000000D+01
      0.207799843750D+05-0.155530166626D+01-0.186264514923D-08 0.000000000000D+00
24 93    8    7 15 15    0.0 0.176711939275D-03 0.109139364213D-10 0.544500000000D+05
      0.204199819336D+05 0.176556110382D+01 0.279396772385D-08 0.000000000000D+00
     -0.796999316406D+04-0.311827659607D+00 0.000000000000D+00 0.100000000000D+01
      0.130460561523D+05-0.295512390137D+01-0.931322574615D-09 0.000000000000D+00
```

----|---1|0---|---2|0---|---3|0---|---4|0---|---5|0---|---6|0---|---7|0---|---8|

+--+
| TABLE A13 |
| GLONASS OBSERVATION FILE - EXAMPLE |
+--+

----|---1|0---|---2|0---|---3|0---|---4|0---|---5|0---|---6|0---|---7|0---|---8|

```
     2                    OBSERVATION  DATA       R  (GLONASS)             RINEX  VERSION  /
TYPE
XXRINEXO V1.1           AIUB                    27-AUG-93 07:23       PGM / RUN BY / DATE
TST1                                                                  MARKER NAME
VIEWEG                        BRAUNSCHWEIG                                OBSERVER  /
AGENCY
100                        XX-RECEIVER             1.0                    REC # / TYPE / VERS
101                        XX-ANTENNA                                      ANT # / TYPE
  3844808.114       715426.767      5021804.854                          APPROX POSITION XYZ
        1.2340            .0000            .0000                          ANTENNA: DELTA H/E/N
     1     1                                                               WAVELENGTH FACT L1/2
     2    C1    L1                                                         # / TYPES OF OBSERV
    10                                                                     INTERVAL
  1993     8    23    14    24    40.049000         GLO                   TIME OF FIRST OBS
                                                                           END OF HEADER

 93    8 23 14 24 40.0490000    0    3    2    1 21
  23986839.824            20520.565 5
  23707804.625            19937.231 5
  23834065.096            -9334.581 5
 93    8 23 14 24 50.0490000    0    3    2    1 21
  23992341.033            49856.525 5
  23713141.002            48479.290 5
  23831189.435           -24821.796 5
 93    8 23 14 25     .0490000    0    3    2    1 21
  23997824.854            79217.202 5
  23718494.110            77092.992 5
  23828329.946           -40219.918 5
 93    8 23 14 25 10.0490000    0    5    2    5 17    1 21
  24003328.910           108602.422 5
  24933965.449           -19202.780 5
  22203326.578            -2987.327 5
  23723851.686           105777.849 5
  23825485.526           -55529.205 5
 93    8 23 14 25 20.0490010    0    5    2    5 17    1 21
```

```
   24008828.023          138012.178 5
   24927995.616          -51188.500 5
   22202547.907           -7213.298 5
   23729236.758          134533.636 5
   23822662.277          -70749.590 5
 93    8 23 14 25 30.0490000    0    5    2    5 17    1 21
   24014330.779          167446.477 5
   24922041.288          -83151.666 5
   22201767.457          -11388.909 5
   23734633.024          163360.131 5
   23819848.894          -85881.102 5

----|---1|0---|---2|0---|---3|0---|---4|0---|---5|0---|---6|0---|---7|0---|---8|


+------------------------------------------------------------------------------+
|                                TABLE A14                                     |
|                MIXED GPS/GLONASS OBSERVATION FILE - EXAMPLE                  |
+------------------------------------------------------------------------------+

----|---1|0---|---2|0---|---3|0---|---4|0---|---5|0---|---6|0---|---7|0---|---8|

       2                    OBSERVATION  DATA        M  (MIXED)              RINEX  VERSION  /
TYPE
YYRINEXO V2.8.1 VM    AIUB                    19-FEB-97 13:59       PGM / RUN BY / DATE
TST2                                                                 MARKER NAME
001-02-A                                                             MARKER NUMBER
JIM                         Y-COMPANY                                OBSERVER / AGENCY
1                           YY-RECEIVER             2.0.1            REC # / TYPE / VERS
1                           GEODETIC L1                              ANT # / TYPE
   3851178.1849     -80151.4072    5066671.1013                     APPROX POSITION XYZ
         1.2340          0.0000          0.0000                     ANTENNA: DELTA H/E/N
       1       0                                                     WAVELENGTH FACT L1/2
       2      C1      L1                                             # / TYPES OF OBSERV
      10                                                             INTERVAL
      11                                                             LEAP SECONDS
   1997       2       6      11      53      0.000000         GPS    TIME OF FIRST OBS
                                                                     END OF HEADER
 97   2    6 11 53    0.0000000    0 14G23G07G02G05G26G09G21R20R19R12R02R11
                                     R10R03
   22576523.586     -11256947.60212
   22360162.704     -16225110.75413
   24484865.974      14662682.882 2
   21950524.331     -13784707.24912
```

```
  22507304.252        9846064.848 2
  20148742.213      -20988953.712 4
  22800149.591      -16650822.70012
  19811403.273      -25116169.741 3
  23046997.513       -3264701.688 2
  22778170.622    -821857836.745 1
  22221283.991    -988088156.884 2
  19300913.475     -83282658.19013
  20309075.579    -672668843.84713
  23397403.484    -285457101.34211
 97    2    6 11 53 10.0000000    0 14G23G07G02G05G26G09G21R20R19R12R02R11
                                      R10R03
  22578985.016     -11244012.910 2
  22359738.890     -16227337.841 2
  24490324.818      14691368.710 2
  21944376.706     -13817012.849 2
  22512598.731       9873887.580 2
  20147322.111     -20996416.338 4
  22798942.949     -16657163.594 2
  19812513.509     -25110234.795 3
  23053885.702      -3227854.397 2
  22770607.029    -821898566.774 1
  22222967.297    -988079145.989 2
  19297913.736     -83298710.38413
  20313087.618    -672647337.04113
  23392352.454    -285484291.40311

----|---1|0---|---2|0---|---3|0---|---4|0---|---5|0---|---6|0---|---7|0---|---8|
```